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PATENT

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

plicant:

Anastasio et al.

Serial No.:

10/087,226

Filed:

March 1, 2002

For:

METHOD FOR DETERMINATION OF

SPATIAL TARGET PROBABILITY USING

A MODEL OF MULTISENSORY PROCESSING BY THE BRAIN

Art Unit:

2857

Examiner:

Unassigned

I hereby certify that this paper is being deposited with the United States Postal Service as FIRST-CLASS mail in an envelope addressed to: Assistant Commissioner for Patents, Washington, D.C. 20231, on this datg.

Registration No. _

Date F-CLASS.WCM

Appr. February 20, 1998

Attorney for Applicant

INFORMATION DISCLOSURE STATEMENT

Assistant Commissioner for Patents Washington, D.C. 20231

Sir:

follows:

In accordance with 37 C.F.R. §§1.56, 1.97 and 1.98, Applicant through counsel herewith submits copies of the publications as set forth in the attached form PTO-1449 as

,	Ţ	I.S. PATENT DOCI	<u>UMENTS</u>	`
Exam	DOCUMENT NO.	<u>PATENTEE</u>	PUBLICATION DATE	CLASS/SUB
len	6,115,480	Washizawa	September 5, 2000	382/228
un	6,226,409	Cham et al.	May 1, 2001	3821228
w	6,314,204	Cham et al.	November 6, 2001	382/103
Examiner 07 Juntes Data 5/27 2004				

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	OTHER DOCUMENTS			
or	Anastasio, T.J., Patten, P.E., Belkacem-Boussaid, K.: <u>Using Bayes' rule to model multisensory enhancement in the superior colliculus</u> . <i>Neural Computation</i> , 12: 1165-1187. (2000).			
wn	Grossberg, S., Roberts, K., Aguilar, M., Bullock, D.: <u>A neural model of multimodal adaptive saccadic eye movement control by superior colliculus</u> . <i>Journal of Neuroscience</i> , 17: 9706-9725. (1997).			
ws	Pearson, J.L., Gelfand, J.J., Sullivan, W.E., Peterson, R.M., Spence, L.D.: Neural network approach to sensor fusion. SPIE Sensor Fusion, 931: 103-108. (1988).			
	Rucci, M., Tononi, G., Edelman, G.M.: Registration of neural maps through value-dependent learning: modeling the alignment of auditory and visual maps in the barn owl's optic tectum. Journal of Neuroscience, 17: 334-3452. (1997).			
u	Rucci, M., Edelman, G.M., Wray, J.: <u>Adaptation of orienting behavior: from the barn owl to a robotic system</u> . <i>IEEE Transactions on Robotics and Automation</i> , 15: 16-110. (1999).			
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